Quantization for Low-Rank Matrix Recovery

Eric Lybrand, Rayan Saab



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Overview

Low Rank Matrix Recovery Motivation Intuition Shortcomings of Analog Theory

Quantization Memoryless Scalar Quantization $\Sigma\Delta$ Quantization

Compressed Sensing and Quantization

Addendum



Quantization

Low Rank Matrix Recovery

Suppose $\mathcal{X} = \{X \in \mathbb{R}^{n_1 \times n_2} : \operatorname{rank}(X) \le k \ll n_1, n_2\}$

¹www-bcf.usc.edu/ Eric Lybrand, Rayan Saab



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Global Positioning, Sensor Localization

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Global Positioning, Sensor Localization

Collaborative Filtering

Quantum State Tomography, X-ray Crystallography

$$y_i = |\langle a_i, x \rangle|^2 = \langle a_i a_i^*, xx^* \rangle =: \mathcal{M}(xx^*)$$



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Natural first guess:

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Problem: Solving the above is NP-Hard Take convex relaxation (Maryam Fazel, '02)

$$X^{\sharp} := \arg\min_{Z} \|Z\|_{*} \text{ subject to } \mathcal{M}(Z) = y,$$

 $\|Z\|_{*} = \sum_{j=1}^{r} \sigma_{j}(Z)$



Nuclear Norm Intuition

Low rank matrices have few singular values, i.e. vector of singular values is sparse



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Low rank matrices have few singular values, i.e. vector of singular values is sparse Use ℓ_1 minimization





Random \mathcal{M} Work Well

Theorem (E. Candès, Y. Plan, '10)

Suppose $m \ge Ck \max\{n_1, n_2\}$, and let $\mathcal{M}(X) := \sum_{j=1}^m \langle A_i, X \rangle$ where A_i are matrices with i.i.d. Gaussian entries. Then with high probability on the draw of \mathcal{M} the following is true for all $X \in \mathbb{R}^{n_1 \times n_2}$ with rank $(X) \le k$: X is the unique minimizer of

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More generally, linear maps which satisfy the matrix Restricted Isometry Property work well.



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How should we represent the continuum with a finite set?

Are the previous results robust to quantization error?



| Low Rank Matrix Recovery | Quantization | Compressed Sensing and Quantization | Addendum |
|--------------------------|--------------|-------------------------------------|----------|
| MSQ | | | |

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In the simplest case, take

$$\mathcal{Q}: \mathbb{R} \to \{\pm 1\}$$
 $\mathcal{D}: \{\pm 1\} \to \mathbb{R}$
 $\mathcal{Q}(y) = \operatorname{sign}(y)$ $\mathcal{D}(q) = q$



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Control error in recovering X by increasing size of \mathcal{A} (resp. bits) so that $\mathcal{D} \circ \mathcal{Q}(y) \approx y$.



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Problem: It could be expensive to increase the number of bits used



Oversampling

- If the number of bits is fixed, try taking more measurements **Intuition:** Measurements sign($\langle A_j, X \rangle$) defines a half-space X lies in.
- ${\sf Minimizing} \ {\sf quantization} \ {\sf error} \ \Longleftrightarrow \ {\sf minimizing} \ {\sf volumes}$



The Shortcomings of MSQ

Volume of regions (i.e. reconstruction error) decay like m^{-1} Vivek Goyal et al ('98): reconstruction error from MSQ quantized frame coefficients can't decay faster than $O(m^{-1})$.



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 $\|y-q\|_2 \le \varepsilon$, then $\|x-\hat{x}\|_2 \le \frac{c_1}{\sqrt{m}}\varepsilon$.





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Alphabet resolution $\beta \implies ||y - q||_2 \le \sqrt{m\beta} \implies$ $||x - \hat{x}||_2 \le c_1\beta$ i.e. the error bound does not decrease with *m*.





Proposed by Inose & Yasuda, 1963 for quantizing bandlimited functions

Keeps track of r previous quantization errors in a state variable u to "shape" the quantized values

$$q_i = Q(\rho_r(u_{i-1}, \dots, u_{i-r}, y_i, \dots, y_{i-r+1}))$$

$$D^r u = y - q, \quad (Du)_i = u_i - u_{i-1}$$



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For example, when r = 1,

$$q_i = \mathcal{Q}(y_i + u_{i-1})$$
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For example, could use equispaced grid where for some fixed L > 0 and resolution $\beta > 0$

$$\mathcal{A} := \{\pm (j - 1/2)\beta, \ j \in [L]\}.$$

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Trade off between bit complexity of alphabet and stability constant.



A More General View of Noise Shaping

 $\Sigma\Delta$ pushes quantization error of previous measurements forward "in time."

 $^{3}\mbox{P.}$ T. Boufounos, "Quantization and erasures in frame representations." Eric Lybrand, Rayan Saab



A More General View of Noise Shaping

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More general noise shaping could involving pushing quantization error for ℓ^{th} coefficient to the ℓ_k^{th} coefficient to compensate (Boufounos, 2006).



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The Perks of Noise Shaping: Sparse Vectors

Theorem (R. Saab, R. Wang, O. Yilmaz, 2015)

Let $A \in \mathbb{R}^{m \times N}$ be a Gaussian matrix with $m \ge C_1 k \log(eN/k)$. Then with high probability the following is true for any k-sparse $x \in \mathbb{R}^N$: let $q = Q_{\Sigma\Delta}^{(r)}(Ax)$. The solution

$$\hat{x} := \arg\min_{z} \|z\|_{1} \ s.t. \ \|D^{-r}(Az - q)\|_{2} \leq \gamma(r)\sqrt{m}$$

satisfies

$$\|\hat{x} - x\|_2 \le C_2 \beta \left(\frac{m}{\ell}\right)^{-r+1/2}$$



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Result is stable w.r.t noise. Result is robust to sparsity assumption.



Theorem (E.L. and R. Saab, 2018)

Let $\mathcal{M}: \mathbb{R}^{n_1 \times n_2} \to \mathbb{R}^m$ be a sub-Gaussian linear map.





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$$(X^{\sharp}, \nu^{\sharp}) := \arg\min_{(Z, \nu)} \|Z\|_* \quad s.t. \quad \|D^{-r}(\mathcal{M}(Z) + \nu - q)\|_2 \le \gamma(r)\sqrt{m}$$

and $\|\nu\|_2 \le \varepsilon\sqrt{m}.$



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$$\begin{aligned} (X^{\sharp},\nu^{\sharp}) &:= \arg\min_{(Z,\nu)} \|Z\|_* \quad s.t. \ \|D^{-r}(\mathcal{M}(Z)+\nu-q)\|_2 \leq \gamma(r)\sqrt{m} \\ and \ \|\nu\|_2 \leq \varepsilon\sqrt{m}. \end{aligned}$$

Then X^{\sharp} satisfies

$$\|X^{\sharp} - X\|_{F} \lesssim_{r} \left(\frac{m}{\ell}\right)^{-r+1/2} \beta + \frac{\sigma_{k}(X)_{*}}{\sqrt{k}} + \sqrt{\frac{m}{\ell}} \epsilon.$$



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New Goal: Formulate a corresponding vector optimization problem where error between minimizer and truth is $||W||_F$.





Let
$$W:=U_W\Sigma_WV_W^*$$
, and set $X_1:=-U_W\Sigma_XV_W^*$





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$$\mathcal{M}_{U_W,V_W}(x) := \mathcal{M}(U_W \operatorname{diag}(x) V_W^*)$$
, and
 $y := D^{-r} (\mathcal{M}_{U_W,V_W}(-\vec{\sigma}(X)) + e) + u.$





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 $y := D^{-r} (\mathcal{M}_{U_W,V_W}(-\vec{\sigma}(X)) + e) + u.$

Show $\vec{\sigma}(W) - \vec{\sigma}(X)$ is feasible to the vector optimization problem with $A = M_{U_W, V_W}$ and $D^{-r}q = y$.





Low Rank Matrix Recovery Quantization Compressed Sensing and Quantization Addendum

Use a lemma from Oymak et al (2011) which buys us

$$\|ec{\sigma}(W) - ec{\sigma}(X)\|_1 = \|X_1 + W\|_* \le \|X_1\|_* = \|ec{\sigma}(X)\|_1$$



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All that's left is to show that $\frac{1}{\sqrt{\ell}}P_{\ell}V^*M_{U_W,V_W}$ satisfies the RIP for all unitary U_W, V_W , as then we can invoke the theorem for vector recovery.



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We use the chaining technique as proposed by Talagrand.

Root Exponential Accuracy

Corollary (E.L. and R. Saab, 2018)

Let $q = Q_{\Sigma\Delta}^{(r)}(\mathcal{M}(X))$ denote quantized noiseless measurements and $X \in \mathbb{R}^{n_1 \times n_2}$ with rank(X) = k. Then there exist constants $c, c_1, C_1, C_2 > 0$ so that when

$$\lambda := \frac{m}{\lceil ck \max(n_1, n_2) \rceil}$$
$$r := \left\lfloor \frac{\lambda}{2C_1 e} \right\rfloor^{1/2}$$
$$q := Q_{\Sigma\Delta}^r(\mathcal{M}(X)).$$

the minimizer X^{\sharp} satisfies $\|X^{\sharp} - X\|_{F} \lesssim \beta e^{-c_{1}\sqrt{\lambda}}$.

Exponential Accuracy with Random Encoding

Corollary (E.L. and R. Saab, 2018)

Let $B : \mathbb{R}^m \to \mathbb{R}^L$ be a Bernoulli random matrix whose entries are ± 1 . Whenever $m \gtrsim_r L \gtrsim_r k \max(n_1, n_2)$ the following is true w.h.p. on the draw of \mathcal{M} and B: the solution of

$$(\hat{X}, \hat{\nu}) := \arg\min_{(Z, \nu)} \|Z\|_{*} \quad s.t. \ \|BD^{-r}(\mathcal{M}(Z) + \nu - q)\|_{2} \le 3m\gamma(r)$$

and $\|\nu\|_{2} \le \epsilon\sqrt{m}.$

satisfies

$$\|\hat{X} - X\|_F \lesssim \left(\frac{m}{L}\right)^{-r/2+3/4} \beta + \frac{\sigma_k(X)_*}{\sqrt{k}} + \sqrt{\frac{m}{L}} \varepsilon.$$



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For noiseless measurements of rank k matrices, this means reconstruction error decays exponentially w.r.t. rate (number of bits).



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Random encoding "reduces complexity" of alphabet \mathcal{A} .







Numerical Illustrations



Experimental DL: reconstruct rank 5, 20×20 Gaussian matrices from noiseless Gaussian measurements, averaged over 20 draws of true matrix.



Future Directions

Taking sub-gaussian measurements is, in general, slow. Do the results hold for partial random circulant matrices, etc?



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How can we modify these results to apply in the matrix completion setting?

Experiments show the exponent for noiseless encoding bound

$$\|\hat{X} - X\|_F \lesssim \left(\frac{m}{L}\right)^{-r/2+3/4}$$

is sub-optimal. Can we prove that it holds with the bound $\left(\frac{m}{L}\right)^{-r+3/4}$?



| | Compressed Sensing and Quantization | |
|--|-------------------------------------|--|
| | | |

Fin



Theorem (R. Saab, R. Wang, O. Yilmaz, 2015)

Let $A \in \mathbb{R}^{m \times N}$, $P_{\ell} : \mathbb{R}^m \to \mathbb{R}^m$ the projection onto the first ℓ coordinates, and V^* as in the singular value decomposition of D^{-r} . Suppose that $\frac{1}{\sqrt{\ell}}P_{\ell}V^*A$ has the vector-RIP of order k and constant $\delta_k < 1/9$. Then any feasible \hat{x} of

$$(\hat{x}, \hat{
u}) := rg\min_{(z,
u)} \|z\|_1 \quad s.t. \quad \|D^{-r}(Az +
u - q)\|_2 \le \gamma(r)\sqrt{m}$$

and $\|
u\|_2 \le \varepsilon$

with $\|\hat{x}\|_1 \le \|x\|_1$ and q satisfying $Ax + e - D^r u = q$ with $\|u\|_{\infty} \le \gamma(r) < \infty$ and $\|e\|_2 \le \varepsilon$ satisfies

$$\|\hat{x}-x\|_2 \leq C\left(\left(\frac{m}{\ell}\right)^{-r+1/2}\beta + \frac{\sigma_k(x)_1}{\sqrt{k}} + \sqrt{\frac{m}{\ell}}\epsilon\right),$$

where $\sigma_1(\mathbf{y})_1 = \operatorname{argmin}_{\text{Eric Lybrand, Rayan Saab}} \|\mathbf{y} - \mathbf{z}\|_1$



A Stronger RIP

Definition

A linear map $\mathcal{M} : \mathbb{R}^{n_1 \times n_2} \to \mathbb{R}^m$ satisfies the matrix RIP of order k with constant δ_k if for any matrix X with rank $(X) \le k$

 $(1 - \delta_k) \|X\|_F^2 \le \|\mathcal{M}(X)\|_2^2 \le (1 + \delta_k) \|X\|_F^2$



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Lemma (S. Oymak, K. Mohan, M. Fazel, B. Hassibi, 2011)

If \mathcal{M} satisfies the matrix RIP of order k with constant δ_k , then for any unitary matrices U, V the linear map $\mathcal{M}_{U,V}$ satisfies the vector RIP of order k with constant δ_k .



So it suffices to show that the linear map $rac{1}{\sqrt{\ell}}P_\ell V^*\mathcal{M}$ satisfies the matrix RIP.



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Consider the stochastic process

$$Z_X := \left| \frac{1}{\ell} \| P_\ell V^* \mathcal{M}(X) \|_F^2 - \| X \|_F^2 \right|$$



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Goal: Control

$$\mathbb{P}\left(\sup_{X} Z_X \geq t\right)$$



Motivating Idea: Suppose that X were drawn from a finite set T. We could always union bound:

$$\mathbb{P}\left(\sup_{X\in\mathcal{T}}Z_X\geq t\right)\leq \sum_{X\in\mathcal{T}}\mathbb{P}\left(Z_X\geq t\right)$$



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Built off of an increment property: it is assumed that there exists a metric d so that

$$\mathbb{P}\left(|Z_X - Z_Y| \ge t
ight) \le 2\exp\left(rac{-t^2}{d^2(X,Y)}
ight).$$


The Generic Chaining

Successively approximate Z_X by

$$Z_X = Z_X - Z_{\pi_1(X)} + Z_{\pi_1(X)} = Z_X - \sum_j Z_{\pi_j(X)} - Z_{\pi_{j-1}(X)}$$

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The Generic Chaining

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Use the increment property on each of the residuals $Z_{\pi_j(X)} - Z_{\pi_{j-1}(X)}$ and union bound over the fibers of π_j .



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The low dimensionality of the above set is what allows us to undersample and obtain the matrix RIP.

